

CGMS-36, JAXA-WP-01 Prepared by JAXA Agenda Item: B.3 Discussed in Plenary

# Update on Advanced Land Observing Satellite (ALOS) - Daichi

The current status of JAXA's Advanced Land Observing Satellite (ALOS) – Daichi is updated. ALOS is a currently routinely operated polar orbiting Earth Observation Satellite managed by JAXA. The ALOS Data are available via ALOS Data nodes dedicated to each region. Contribution to Sentinel Asia is also reported.



# 1. Overview

Advanced Land Observing Satellite (ALOS) have been successfully launched on an H-IIA launch vehicle from the Tanegashima Space Center, Japan on 24 January, 2006, and renamed Daichi. The routine operation of all the sensors is going well currently.

ALOS's objectives are:

to provide maps for Japan and other countries including those in the Asian-Pacific region (Cartography)

to perform regional observation for "sustainable development", harmonization between Earth environment and development (Regional Observation),

to conduct disaster monitoring around the world (Disaster Monitoring) including Sentinel Asia and Disaster Charter,

to survey natural resources (Resources Surveying),

to develop technology necessary for future Earth observing satellite (Technology Development)



Figure 1: ALOS Configuration

The ALOS has three remote-sensing instruments: the Panchromatic Remote-sensing Instrument for Stereo Mapping (PRISM) for digital elevation mapping, the Advanced Visible and Near Infrared Radiometer type 2 (AVNIR-2) for precise land coverage observation, and the Phased Array type L-band Synthetic Aperture Radar (PALSAR) for day-and-night and all-weather land observation. In order to utilize fully the data obtained by these sensors, the ALOS was designed with two advanced technologies: the former is the high speed and large capacity mission data handling technology, and the latter is the precision spacecraft position and attitude determination capability. They will be essential to high-resolution remote sensing satellites in the next decade.



| Launch Date                        | January 24, 2006                         |  |  |
|------------------------------------|--|--|--|
| Launch Vehicle                     | H-IIA                                    |  |  |
| Launch Site                        | Tanegashima Space Center                 |  |  |
| Spacecraft Mass                    | Approx. 4 tons                           |  |  |
| Generated Power                    | Approx. 7 kW (at End of Life)            |  |  |
| Design Life                        | 3 -5 years                               |  |  |
| Orbit                              | Sun-Synchronous Sub-Recurrent            |  |  |
|                                    | Repeat Cycle: 46 days                    |  |  |
|                                    | Sub Cycle: 2 days                        |  |  |
|                                    | Altitude: 691.65 km (at Equator)         |  |  |
|                                    | Inclination: 98.16 deg.                  |  |  |
| Attitude Determination<br>Accuracy | 2.0 x 10 <sup>-₄</sup> degree (with GCP) |  |  |
| Position Determination<br>Accuracy | 1m (off-line)                            |  |  |
|                                    | 240Mbps (via Data Relay Technology       |  |  |
| Data Rate                          | Satellite)                               |  |  |
|                                    | 120Mbps (Direct Transmission)            |  |  |
| <b>Onboard Data Recorder</b>       | Solid-state data recorder (90Gbytes)     |  |  |

# **Table 1: ALOS Characteristics**

## 2. Observation Instruments

#### 2.1 Panchromatic Remote-sensing Instrument for Stereo Mapping (PRISM)

The Panchromatic Remote-sensing Instrument for Stereo Mapping (PRISM) is a panchromatic radiometer with 2.5m spatial resolution at nadir. Its extracted data will provide a highly accurate digital surface model (DSM).

PRISM has three independent optical systems for viewing nadir, forward and backward producing a stereoscopic image along the satellite's track. Each telescope consists of three mirrors and several CCD detectors for push-broom scanning. The nadir-viewing telescope covers a width of 70km; forward and backward telescopes cover 35km each.

The telescopes are installed on the sides of the optical bench with precise temperature control. Forward and backward telescopes are inclined +24 and -24 degrees from nadir to realize a base-to-height ratio of 1.0. PRISM's wide field of view (FOV) provides three fully overlapped stereo (triplet) images of a 35km width without mechanical scanning or yaw steering of the satellite. Without this wide FOV, forward, nadir, and backward images would not overlap each other due to the Earth's rotation.







| Number of Bands   | 1 (Panchromatic)  |  |  |
|---|---|--|--|
| Wavelength  | 0.52 to 0.77 micrometers                                      |  |  |
| Number of Optics  | 3 (Nadir; Forward; Backward)                                  |  |  |
| Base-to-Height ratio  | 1.0 (between Forward and Backward view)                       |  |  |
| Spatial Resolution  | 2.5m (at Nadir)   |  |  |
| Swath Width   | 70km (Nadir only) / 35km (Triplet mode)                       |  |  |
| <b>S/N</b> >70  |   |  |  |
| MTF >0.2  |   |  |  |
| Number of Detectors28000 / band (Swath Width 70km)<br>14000 / band (Swath Width 35km) |   |  |  |
| Pointing Angle  | -1.5 to +1.5 degrees<br>(Triplet Mode, Cross-track direction) |  |  |
| Bit Length  | 8 bits  |  |  |

## **Table 2: PRISM Characteristics**

Note: PRISM cannot observe areas beyond 82 degrees south and north latitude.

# Table 3: PRISM Observation Modes

| Mode 1         Triplet observation mode using Forward Nadir, and Backward views (Swath wid 35km) |                                  |  |  |
|--|----------------------------------|--|--|
| Mode 2   | Nadir (70km) + Backward (35km)   |  |  |
| Mode 3   | Nadir (70km)                     |  |  |
| Mode 4   | Nadir (35km) + Forward (35km)    |  |  |
| Mode 5   | Nadir (35km) + Backward (35km)   |  |  |
| Mode 6   | Forward (35km) + Backward (35km) |  |  |
| Mode 7   | Nadir (35km)                     |  |  |
| Mode 8   | Forward (35km)                   |  |  |
| Mode 9   | Backward (35km)                  |  |  |





Figure 3: Swath of PRISM

# 2.2 Advanced Visible and Near Infrared Radiometer type 2 (AVNIR-2)

The Advanced Visible and Near Infrared Radiometer type 2 (AVNIR-2) is a visible and near infrared radiometer for observing land and coastal zones. It provides better spatial land-coverage maps and land-use classification maps for monitoring regional environments. AVNIR-2 is a successor to AVNIR that was on board the Advanced Earth Observing Satellite (ADEOS), which was launched in August 1996.

Its instantaneous field-of-view (IFOV) is the main improvement over AVNIR. AVNIR-2 also provides 10m spatial resolution images, an improvement over the 16m resolution of AVNIR in the multi-spectral region. Improved CCD detectors (AVNIR has 5,000 pixels per CCD; AVNIR-2 7,000 pixels per CCD) and electronics enable this higher resolution. A cross-track pointing function for prompt observation of disaster areas is another improvement. The pointing angle of AVNIR-2 is +44 and - 44 degree.



Figure 4: AVNIR-2 Configuration



| Number of Bands     | 4                                 |  |  |
|---------------------|-----------------------------------|--|--|
|                     | Band 1: 0.42 to 0.50 micrometers  |  |  |
| May calle in with   | Band 2 : 0.52 to 0.60 micrometers |  |  |
| wavelength          | Band 3 : 0.61 to 0.69 micrometers |  |  |
|                     | Band 4 : 0.76 to 0.89 micrometers |  |  |
| Spatial Resolution  | 10m (at Nadir)                    |  |  |
| Swath Width         | 70km (at Nadir)                   |  |  |
| S/N                 | >200                              |  |  |
| MTC                 | Band 1 through 3 : >0.25          |  |  |
|                     | Band 4 : >0.20                    |  |  |
| Number of Detectors | 7000/band                         |  |  |
| Pointing Angle      | - 44 to + 44 degree               |  |  |
| Bit Length          | 8 bits                            |  |  |

# Table 4: AVNIR-2 Characteristics

Note: AVNIR-2 cannot observe the areas beyond 88.4 degree north latitude and 88.5 degree south latitude.



Figure 5: Swath of AVNIR-2

# 2.3 Phased Array type L-band Synthetic Aperture Radar (PALSAR)

The Phased Array type L-band Synthetic Aperture Radar (PALSAR) is an active microwave sensor using L-band frequency to achieve cloud-free and day-and-night land observation. It provides higher performance than theJERS-1's synthetic aperture radar (SAR). Fine resolution in a conventional mode, but PALSAR will have another advantageous observation mode. ScanSAR, which will enable us to acquire a 250 to 350km width of SAR images (depending on the number of scans) at the expense of spatial resolution. This swath is three to five times wider than conventional SAR images. The development of the PALSAR is a joint project between JAXA and the Japan Resources Observation System Organization (JAROS).

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Figure 6: PALSAR Configuration

| Mode                              | Fine   |                   | ScanSAR              | Polarimetric<br>(Experimental<br>mode)*1 |  |
|-----------------------------------|--|-------------------|----------------------|--|--|
| Center<br>Frequency               |  |                   | 1270 MHz(L-band)     |  |  |
| Chirp<br>Bandwidth                | 28MHz  | 14MHz             | 14MHz,28MHz          | 14MHz                                    |  |
| Polarization                      | HH or VV   | HH+HV or<br>VV+VH | HH or VV             | HH+HV+VH+VV                              |  |
| Incident<br>angle                 | 8 to<br>60deg.   | 8 to<br>60deg.    | 18 to 43deg.         | 8 to 30deg.                              |  |
| Range<br>Resolution               | 7 to 44m   | 14 to 88m         | 100m<br>(multi look) | 24 to 89m                                |  |
| Observation<br>Swath40 to<br>70km |  | 40 to<br>70km     | 250 to 350km         | 20 to 65km                               |  |
| Bit Length                        | 5 bits   | 5 bits            | 5 bits               | 3 or 5bits                               |  |
| Data rate                         | ate 240Mbps 240Mbps  |                   | 120Mbps,240Mbps      | 240Mbps                                  |  |
| NE sigma<br>zero *2               | < -23dB<br>(Swath Width 70km)<br>< -25dB<br>(Swath Width 60km) |                   | < -25dB              | < -29dB                                  |  |
| S/A *2,*3                         | > 16dB<br>(Swath Width 70km)<br>> 21dB<br>(Swath Width 60km)   |                   | > 21dB               | > 19dB                                   |  |
| Radiometric accuracy              | scene: 1dB / orbit: 1.5 dB                                     |                   |                      |  |  |

Table 5: PALSAR Characteristic

Note: PALSAR cannot observe the areas beyond 87.8 deg. north latitude and 75.9 deg. south latitude when the off-nadir angle is 41.5 deg.

\*1 Due to power consumption, the operation time will be limited.

- \*2 Valid for off-nadir angle 34.3 deg. (Fine mode),
  - 34.1 deg. (ScanSAR mode),
  - 21.5 deg. (Polarimetric mode)

\*3 S/A level may deteriorate due to engineering changes in PALSAR.





Figure 7: Swath of PALSAR

# 3. Data Level definitions

Definitions of ALOS instrument data levels are shown in the tables below. Level 1 products are defined as Standard Products of ALOS.

| Level | Definition                 | Option | Note       |
|-------|----------------------------|--------|------------|
| Raw   | Raw Demodulated bit stream |        | Packetized |

| (1) PRISM |  |
|-----------|--|
|-----------|--|

| Level | Definition  | Option  | Note  |
|-------|---|---|---|
| 0     | Frame synchronization and PN decoding of CADUs<br>(Channel Access Data Units) and Reed-Solomon<br>error detection and correction of VCDUs (Virtual<br>Channel Data Units)<br>Extracted mission telemetry, orbit and attitude data<br>are stored on separate files |   | Distribution level<br>for Data Nodes<br>Separate data<br>files for each<br>VCID |
| 1A    | Uncompressed, reconstructed digital counts<br>appended with radiometric calibration coefficients and<br>geometric correction coefficients (appended but not<br>applied)<br>Individual files for forward, nadir and backward<br>looking data                       |   | Separate image<br>files for each<br>CCD   |
| 1B1   | Radiometrically calibrated data at sensor input   |   | Separate image<br>files for each<br>CCD   |
| 1B2   | Geometrically corrected data<br>Option<br>G: Systematically Geo-coded<br>R: Systematically Geo-referenced<br>Option G or R is alternative   | Map projection<br>Resampling<br>Pixel spacing | Single image file   |



# (2) AVNIR-2

| Level | Definition  | Option  | Note  |
|-------|---|---|---|
| 0     | Frame synchronization and PN decoding of CADUs<br>(Channel Access Data Units) and Reed-Solomon<br>error detection and correction of VCDUs (Virtual<br>Channel Data Units)<br>Extracted mission telemetry, orbit and attitude data<br>are stored on separate files |   | Distribution level<br>for Data Nodes<br>Separate data<br>files for each<br>VCID |
| 1A    | Uncompressed, reconstructed digital counts<br>appended with radiometric calibration coefficients and<br>geometric correction coefficients (appended but not<br>applied)   |   | Separate image<br>files for each<br>band  |
| 1B1   | Radiometrically calibrated data at sensor input   |   | Separate image<br>files for each<br>band  |
| 1B2   | Geometrically corrected data<br>Option<br>G: Systematically Geo-coded<br>R: Systematically Geo-referenced<br>D: Correction with coarse DEM (Japan area only)<br>Option G or R is alternative  | Map projection<br>Resampling<br>Pixel spacing | Separate image<br>files for each<br>band  |

#### (3) PALSAR

| Ì | Level | Definition  | Option  | Note   |
|---|-------|---|---|--|
|   | 0     | Frame synchronization and PN decoding of CADUs<br>(Channel Access Data Units) and Reed-Solomon error<br>detection and correction of VCDUs (Virtual Channel<br>Data Units)<br>Extracted mission telemetry, orbit and attitude data are<br>stored on separate files |   | Distribution level<br>for Data Nodes<br>Separate data files<br>for each VCID |
|   | 1.0   | Reconstructed, unprocessed signal data appended<br>with radiometric and geometric correction coefficients<br>(appended but not applied)   |   | Separate image<br>files for each<br>polarization (HH,<br>VV, HV, VH)         |
|   | 1.1   | Range and azimuth compressed<br>Complex data on slant rang  |   | Separate image<br>files for each<br>polarization (HH,<br>VV, HV, VH)         |
|   | 1.5   | Multi-look processed image projected to map<br>coordinates<br>Option<br>G: Systematically Geo-coded<br>R: Systematically Geo-referenced<br>Option G or R is alternative   | Map projection<br>Resampling<br>Pixel spacing | Separate image<br>files for each<br>polarization (HH,<br>VV, HV, VH)         |

# 4. ALOS Systematic Observation Strategy

The ALOS mission features a systematic observation strategy which comprises pre-launch, systematic global observation plans for all three instruments. The strategy is implemented as a top-level foreground mission and with a prior ity level second only to that of emergency observations.

The observation strategy is developed by JAXA/Earth Observation Research Center (EORC) and aims to provide spatially and temporally consistent, multi-seasonal global coverage, on a repetitive basis, with all three sensors, during the life-time of the ALOS satellite. It is foreseen to result in a comprehensive and homogeneous global archive of PALSAR, PRISM and AVNIR-2 data, in which a consistent time-series for data can be found for any arbitrary point or region on Earth. Presently, such consistent data archives only exist for coarse resolution satellites.



The plans are designed to fulfil the following general acquisition concepts: Spatial and temporal consistency over continental scales at fine resolution; Adequate revisit frequency; Accurate timing: Consistent sensor configuration; Long-term continuity.

While the observation strategy is foreseen to serve the major data needs of both scientific and commercial users, additional acquisition requests can still be placed by individual users (via the ALOS Data Nodes) or Principal Investigators participating in Announcements of Opportunities organized by JAXA and/or the ALOS Data Nodes. As such requests however have lower priority than the strategy observations, users are strongly encouraged to align individual observation requests with the observation strategy in order to avoid programming conflicts and thereby to improve individual request success rates.

# 4.1 PALSAR Observation Strategy

The PALSAR acquisition strategy features routine observations at four pre-selected sensor modes (Table 6). The mode selection represents a compromise solution where scientific requirements, user requests, programmatic aspects and satellite operational constraints have been taken into consideration.

| Sensor mode                      | Polarization    | Off-nadir<br>angle | Pass<br>designation | Coverage                   | Time<br>window | Observation<br>frequency           |
|----------------------------------|-----------------|--------------------|---------------------|----------------------------|----------------|------------------------------------|
| Fine Beam<br>Single pol.         | нн              | 41.5°              | Ascending           | Global                     | Dec-Feb        | 1-2 obs/year                       |
| Fine Beam<br>Dual pol.           | HH+HV           | 41.5°              | Ascending           | Global                     | May-Sept       | 1-4 obs/year                       |
| Fine Beam<br>Polarimatric        | HH+HV+<br>VH+VV | 21.5°              | Ascending           | Regional                   | March-May      | 2 obs/2 years                      |
| ScanSAR<br>5-beam<br>Short burst | нн              | 20.1° -<br>36.5°   | Descending          | (a) Global<br>(b) Regional | Jan-Dec        | (a) 1 obs/year<br>(b) 8 obs/1 year |

 Table 6: PALSAR sensor default modes

To assure spatially and temporally homogeneous data collection over regional scales, acquisitions are planned in units of whole (46-day) repeat cycles, during which only one of the available default modes is selected. The PALSAR strategy is furthermore separated into one plan for ascending (evening) passes, and one for descending (morning) ditto.

#### (1) Ascending acquisitions (evening, ~22.30)

The PALSAR ascending mode plan comprises repetitive, global-scale observations with a constant off-nadir angle of 41.5° in both single polarisation (HH) and dual polarisation (HH+HV). To maintain mode-consistency in the multi-annual time series to be acquired, single-pol observations are scheduled during the northern hemisphere winter, and dual-pol observations around the summer months.

The minimum requirement for any land area on Earth is to perform at least one single-pol and one dual-pol acquisition annually, and in addition, two dual-pol acquisitions during consecutive 46-days cycles on a bi-annual basis to enable interferometric applications. Most areas are however to be acquired significantly more often than this, typically 3-5 times per year. In general, regions in the eastern hemisphere (Asia, Australia, eastern Europe and Africa) within the coverage of the Data Relay Satellite (DRTS) are acquired most frequently, while the western hemisphere (the Americas, western Europe and Africa) is restrained by the recording and down-link capacity of the on-board data recorder (HSSR).



To promote research relating to SAR polarimetry and polarimetric interferometry, polarimetric observation campaigns are planned once every two years, during which selected regions around the globe are acquired in full polarimetric mode during two consecutive cycles. As polarimetric operations at large off-nadir angles are not possible however, acquisitions will be performed at 21.5°.

# (2) Descending acquisitions (morning, ~10.30)

To minimize resource conflicts with PRISM and AVNIR-2, which only can be operated during daytime passes, the descending acquisition plan for PALSAR is principally limited to low data-rate (120 Mbps) ScanSAR observations at HH polarization.

The ScanSAR scenario comprises one global coverage on an annual basis, and in addition - given the LHH-band sensitivity to detect inundation phenomena - intensive monitoring over a number of selected regional-scale wetland environments of global significance. To adequately capture the hydrological changes that occur throughout the year, ScanSAR observations will typically be performed every 46-days during 8-9 consecutive satellite cycles (12-13 months).

# 4.2 PRISM and AVNIR-2 Observation Strategy

PRISM and AVNIR-2 are programmed for repetitive, global-scale observations, and like PALSAR, the observation strategy implemented aims to maintain both spatial and temporal consistency over regional scales. The timing of the regional observations has been determined based on cloud statistics, seasonality and sun elevation, although cloud cover inevitably limits the amount of useful data acquired.

The default mode for PRISM operations is the 3-telescope triplet mode to enable along-track stereo viewing. As the swath width in triplet mode is 35 km, two 46-day cycles are required to achieve a full regional coverage, during which the instrument is tilted alternately (+/-  $1.2^{\circ}$ ) in across-track direction.

The PRISM plan can be summarized as follows:

Odd cycle numbers: +1.2° viewing angle

Even cycles: -1.2° viewing angle

The default mode for AVNIR-2 is nadir view.

For any given region, AVNIR-2 is typically scheduled for "one acquisition during two consecutive cycles", meaning that if an acquisition is successfully programmed the first of the two cycles in question, it will not be included in the plan during the second (regardless of cloud cover).





# 5. ALOS Data System overview

An overview of the ALOS Data System is shown in Figure 8.



#### Figure 8: Overview of the ALOS data system

The primary path for reception of ALOS data is via JAXA's Data Relay Test Satellite, DRTS, at 90.75 degree East longitude (launched 10th September 2002) down-linked to JAXA/Earth Observation Center (EOC) at Hatoyama, where Level 0 data for ALOS will be generated. The receiving station at Tsukuba is a backup path for receptionvia DRTS.

ALOS data may also be down-linked directly by X-band transmission to JAXA's EOC and to JAXA's overseas ground stations as backup options for DRTS transmission. There is also provision for routine X-band transmission of ALOS data to ground stations of the ALOS Data Node partners, including for near real time data utilisation.

# 6. ALOS Data Node (ADN)

Recognising that the total data produced by the ALOS sensors on a daily basis (1 Terabyte) is beyond the capabilities of any single agency or country to attempt to manage, but that there was world-wide interest in the use of that data, JAXA proposed the concept of the ALOS Data Nodes with local archives, as a mechanism for sharing the processing and distribution load.

To promote international data use and operational use of ALOS data, data node organizations are appointed for different regions world-wide. The data node organizations will receive ALOS Level 0 data from JAXA and generate and distribute products to regional users in accordance with their agreement with JAXA. And also the data node organizations will be able to receive ALOS data via X band ground stations by agreement with JAXA.

The benefits of the ADN concept are:



increased capacity for ALOS Data processing and archiving; accelerated scientific and practical use of ALOS data;

increased international co-operation including on validation and science study activities;

enhanced service for potential users of ALOS data.

The ADN concept is envisaged as a new model for the provision of Earth observation missions, bringing mutual benefits for both the funding agency and the global partners involved in the distribution and application of the data.

The current concept envisages 4 Nodes world-wide in order to achieve the necessary global coverage:

| ADN Partners         | General zone of responsibility |  |  |
|----------------------|--------------------------------|--|--|
| ESA*                 | Europe and Africa              |  |  |
| NOAA/ASF             | North and South America        |  |  |
| Geoscience Australia | Oceania                        |  |  |
| JAXA Asia            |                                |  |  |

#### Table 7: ADN Partners and relevant Zones

\*CNES withdrew from the project in September 2003

In addition, GISTDA of Thailand was accepted to the ADN scheme as a 'sub-Node' within Asia, including for direct reception of ALOS data to promote ALOS data utilization.

Each Node is associated with a geographical zone - which defines the physical location of the ALOS users which the Node has a mandate to support as an ADN partner. These zones are approximately defined in Figure 9.



Figure 9: ADN Zone definitions



JAXA appoints a Primary Distributor to take care of data distribution in the Asian Zone and to serve as an interface between JAXA and the Nodes for the management and administration of all issues relating to commercial use of ALOS data for all other Zones.

Remote Sensing Technology Center (RESTEC) is appointed as the PD by JAXA. Thus, RESTEC distributes the ALOS products for commercial use within the Asian Zone.

A Regional Distributor is designated by each Node for commercial distribution of the ALOS products within the relevant Zone.

After Initial Cal./Val. Phase, ALOS routine operation began in the late of October, 2006, and the ALOS Level 0 data are distributed to the Nodes in regular basis. Then, users can obtain the ALOS products through the user's Node.

## 7. Contrubution to Sentinel Asia

The Sentinel Asia (SA) initiative is a collaboration between space agencies and disaster management agencies, applying remote sensing and Web-GIS technologies to assist disaster management in the Asia-Pacific region. It aims to:

- Improve safety in society by ICT and space technology
- Improve speed and accuracy of disaster preparedness and early warning
- Minimize the number of victims and social/economic losses.

SA is a voluntary initiative led by the Asia-Pacific Regional Space Agency Forum (APRSAF) to share disaster information in near-real-time across the Asia-Pacific region, using primarily the Digital Asia (Web-GIS) platform. Its architecture is designed to operate initially as an internet-based, node-distributed information distribution backbone, eventually distributing relevant satellite and in situ spatial information on multiple hazards in the Asia-Pacific region.

A step-by-step approach for implementation of this dissemination system was adopted as follows:

- Step 1: Implementation of the backbone Sentinel Asia data dissemination system as a pilot project, to showcase the value and impact of the technology using standard internet dissemination systems (2006-2007)
- Step 2: Expansion of the dissemination backbone with new satellite communication systems (2008-2012)
- Step 3: Establishment of a comprehensive disaster management support system (2013 onwards)

SA Step1 has achieved its overall goals. The Sentinel Asia website has operated since October 2006. It has served as a good demonstrator project, to share disaster-related information obtained by several Earth observation satellites such as Advanced Land Observing Satellite (ALOS), Indian Remote Sensing Satellites (IRS), Multi-functional Transport Satellite 1R (MTSAT-1R), Terra and Aqua. It also demonstrates recent advances in web-mapping technologies and ICT systems.

SA Step 2 has recently been initiated with the following principles and objectives:

- A contribution from the space community (APRSAF) to disaster management in the Asia-Pacific region
- To promote utilization of disaster-related information obtained by space and remote sensing technology in order to mitigate and prevent damage caused by natural disasters
- To strengthen and succeed Step1, considering the findings and achievements of Step 1 and users' needs
- · A voluntary initiative through the new Joint Project Team

#### Background

According to statistics (by ADRC-Natural Disasters Data Book-2006), the Asia region has been seriously damaged by natural disasters over the last 30 years. This is compounded by its high levels of population (close to 3 billion). Disasters occurring in Asia comprise 37 per cent of the worldwide total, whereas the region has 57 per cent of the global fatalities and 89 per cent of the total victims associated with such disasters.



In view of these circumstances, APRSAF proposed Sentinel Asia in 2005, to showcase the value and impact of Earth observation technologies, combined with near-real-time internet dissemination methods and Web-GIS mapping tools for disaster management support in the Asia-Pacific region. APRSAF was established in 1993, in response to the declaration adopted by the Asia-Pacific International Space Year Conference (APIC) in 1992, to enhance the development of each country's space programme and to exchange views toward future cooperation in space activities in the Asia-Pacific region. It was originally designed to provide opportunities for regional space agencies and associated governmental bodies to exchange technical views, o pinions and information on national space programmes and space resources.

## Framework

SA is promoted with cooperation amongst the space Community (APRSAF), the international community (UN ESCAP, UN OOSA, ASEAN, Asian Institute of Technology (AIT) etc.), the disaster reduction community (Asian Disaster Reduction Center (ADRC) and its member countries) and the Digital Asia Community (Keio University etc.).

To support the implementation of the SA project, a Joint Project Team (JPT) was organized. Membership of the JPT is open to all the APRSAF member countries, disaster prevention organizations and regional/international organizations that are prepared to contribute their experience and technical capabilities, and that wish to participate in technical aspects of disaster information sharing activities.

#### Activities

Sentinel Asia has two main responsibilities:

- 1. Providing disaster-related information in the Asia-Pacific region, such as satellite imagery, and satellite data products through the website.
- 2. Capacity building to develop human resources and a human network to utilize the information provided by the website.
- The main activities of SA are as follows:
- Emergency observation in case of major disasters by Earth observation satellites via observation requests of JPT and ADRC members
- Wildfire monitoring and flood monitoring
- · Capacity building for utilization of satellite images for disaster management.

SA Step 1 operations have been running since October 2006 with the opening of its website (<u>http://dmss.tksc.jaxa.jp/sentinel</u>). JPT consists of 51 organizations from 20 countries and eight international organizations at the time of writing. The Japan Aerospace Exploration Agency (JAXA) is a secretariat of the JPT.

Currently, a website dedicated to SA is open to the public providing the following content:

- Recent disasters and emergency observation
- Hotspots data for wildfire monitoring
- Accumulated precipitation data for flood monitoring in cooperation with the Global Flood Alert System (GFAS)
- MTSAT imagery in cooperation with Japan Meteorological Agency (JMA)
- Capacity building.

JAXA's ALOS satellite and the IRS satellite of the Indian Space Research Organization (ISRO) have carried out emergency observations in the case of major disasters in the Asia-Pacific region. Wildfire is a major and recurring phenomenon that has a serious impact on property and human health, affecting many countries in the region. Compared to other disasters in the area, it does not necessarily cause many immediate fatalities. However, it causes serious impact on property and human health due to smoke. Responding to requirements from Asian countries, wildfire monitoring has been chosen as one of SA's activities. Having accurate information on the location and intensity of the fires, and subsequent control of wildfire, are therefore very important and urgent tasks across the region. SA primarily addresses the issue of near-real-time information distribution on wildfires in the region. Furthermore, its effects are of great relevance both at a regional and global level, and accordingly bear substantial influence on global warming. Flood is also a major and recurring phenomenon affecting many countries in the Asia-Pacfic region, and flood monitoring has been chosen as one of SA's activities. At the moment, SA is



providing accumulated precipitation data from GFAS, MTSAT imagery on Web-GIS and inundated area information observed by satellite.

A good human network has been constructed between the space and disaster reduction communities since operations began in October 2006. At the same time, some difficulties have appeared which need greater attention and more work to resolve, such as narrowband areas in Asia, where it is very hard to see information via the Internet.

#### Sentinel Asia Step 2

At APRSAF-14 held in Bangalore, India in November 2007, the following recommendations on SA were adopted:

- A deeclartion that the efforts of the current JPT have led to the successful completion of the Sentinel Asia pilot project. This pilot project has successfully shared disaster-related information obtained by several Earth observation satellites, especially those of JAXA and ISRO, along with training and technical support.
- A declaration of the launch of the next phase of Sentinel Asia, running from 2008 to 2012, with the goal of expanding utilization of disaster-related information, including environmental changes together with its member countries and international organizations. Increasing the number of Earth observation satellites from the Korea Aerospace Research Institute (KARI), the Geo-Informatics and Space Technology Development Agency (GISTDA) of Thailand, and some other entities, as well as satellite communication.
- An agreement to establish the new JPT for implementation of the second phase of Sentinel Asia early next year, where JAXA will serve as a secretariat.

In response to the APRSAF-14 recommendation, the new JPT meeting was held in Kobe, Japan in June 2008, and the Sentinel Asia Step 2 project was initiated.

The main objectives of 'Sentinel Asia Step 2' are as follows:

(1) Participation of various satellites

In addition to Step 1's Earth observation satellites such as ALOS (JAXA), MTSAT-1R (JMA) and IRS (ISRO), new Earth observation satellites such as the Korean Multi-purpose Satellite (KOMPSAT, KARI), Thai Earth Observation System (THEOS, GISTDA), and communications satellites such as the wideband Internetworking Engineering Test and Demonstration Satellite (WINDS, JAXA) etc. are expected to join.

(2) Improvement of accessibility to information

In addition to data sharing via the Internet in Step 1, information transmission to facilitate access to disaster-related information through various means including demonstration of the use of new-generation communication satellites will be introduced.

(3) Value-added data

A new framework of satellite data analysis is organized to provide analyzed images and easily comprehensible interpretations from images. AIT, ADRC, the Center for Remote Imaging, Sensing and Processing (CRISP, National University of Singapore), among others, are expected to join the framework.

- (4) Expansion of disaster scope SA is expected to contribute to the mitigation of global warming through strengthening its contribution to wildfire management, which has a substantial influence on global warming.
- (5) User expansion

A planned expansion of the user-base to include local disaster authorities in cooperation with organizations such as UN ESCAP.

(6) Enrichment of outreach and capacity building

A new framework to promote outreach and capacity building will be organized. JAXA, ISRO, AIT and ADRC are expected to be among the organizations that join the framework.

Utilization

Page 15 of 13 Sentinel Asia Step 2 aims to broaden the reach of Step 1

